

Quarterly Progress Report:

Project Number and Title: C20.2020: Advanced Sensing Technologies for Practical UAV-Based Condition Assessment
Research Area: Transportation Infrastructure Monitoring and Assessment for Enhanced Life
PI: Dryver Huston, University of Vermont
Co-PI(s): Tian Xia, University of Vermont; Eric Landis, University of Maine; Tzuyang Yu, University of Massachusetts Lowell
Reporting Period: 7/1/21 – 9/30/21
Submission Date: September 30, 2021

Overview:

This is a collaborative research project with the University of Vermont, University of Maine, and University of Massachusetts Lowell. This quarter was the second quarter of activity on the project. Some of the highlights are:

1. Evaluation and development of acoustic sensing techniques for concrete quality assessment – A set of concrete slabs with embedded defects were fabricated and assessed. These defects included styrofoam, bubble-wrap foam, water-dissolved rice paper and rock salt layer, and a mechanically separated delamination. The intent for these slabs is to serve as phantoms for evaluating acoustic test instruments. The styrofoam and water-dissolved rice paper and rock salt layer both performed quite well with audible and measurable frequency shifts occurring over the mock delaminations.

2. Assembly of an acoustic sensor arm for use on a UAV - A prototype lightweight arm with integrated tapper mechanism and microphone sensor has been assembled as a proof of concept. Figure 1 shows the use of acoustic sensor arm being used on concrete slab phantom with embedded defects.





Figure 1. Testing of concrete delamination phantom with acoustic sensor arm and portable data acquisition system.

3. Examination of microwave transceiver for use on UAV – –shows the portable microwave transceiver.

In the past quarter, we investigated the effect of platform motion on SAR images. We used a portable SAR imaging sensor to inspect two laboratory concrete panels inside an anechoic chamber at UML. A wireless accelerometer was installed on the portable SAR imaging sensor to determine the relative displacement (by double integrals) between the radar and concrete panels. Figure 2 shows the two concrete panels used in this SAR imaging experiment. Figure 3 shows the displacement histories of the portable SAR imaging sensor.





Figure 2 (a) Intact concrete panel (50 cm-by-50 cm-by-10 cm) (b) Damaged concrete panels



Figure 3 (a) Hand displacement history in Intact-HP (b) Hand displacement history in Damaged-HP

Next, we collected SAR images by using a stationary positioner (automatic) and by using two hands (manual) are shown in Figure 4. In Figure 4, the effect of platform motion on SAR images is clearly observed. Both phase shift and amplitude change are found in the manually collected SAR images.





Figure 4. (left) SAR images collected by using a positioner / (right) SAR images collected by using two hands

Meeting the Overarching Goals of the Project:

The overarching goals of this project center on the synergistic application of unmanned aerial vehicles (UAVs) with active acoustic sensing (AAS) and synthetic aperture radar (SAR) for the underside inspection of bridge decks. Employing such UAV-AAS-SAR systems may i) reduce inspection cost by more than 50%, ii) improve inspectors' safety, and iii) mitigate traffic interference with little or no traffic control measures needed. The plan is 1) develop an acoustic sensor capable of actively interrogating concrete delamination of bridge decks from underneath, 2) develop a compact radar sensor capable of remotely scanning concrete surface for delamination detection, 3) develop a UAV platform capable of housing the acoustic and the radar sensors for bridge inspection, 4) develop image processing and interpretation algorithms for condition assessment, and 5) work with partners in the bridge inspection industry to guide design decisions to produce a practical and useful system.

Progress in this past quarter advanced the goals of the project with efforts at custom UAV fabrication, acoustic sensing and microwave sensing customized for use as concrete damage detectors deployed on a UAV.

Accomplishments:

Built a prototype acoustic sensor arm and tested on concrete slab phantoms.

Tested the effects of motion similar to that of a UAV on microwave SAR sensing of damage.



Task Progress and Budget:

Table 1: Task Progress						
Task Number	Start Date	End Date	% Complete			
Task 1.1 (Phase 1.A):			<u> </u>			
Survey of Commercial	4/1/21	6/30/21	100			
UAVs						
Task 2.1 (Phase 1.A):						
Design and build	4/1/01	0/01/00				
acoustic sensor arm	4/1/21	3/31/22	45			
(ASA)						
Task 2.2 (Phase 1.A):						
Select and configure	4/1/21	3/31/22	25			
acoustic sensors						
Task 3.1 (Phase 1.A).						
Calibration of baseline						
interference on radar	4/1/21	3/31/22	20			
signals						
Task 3.2 (Phase 1.A):						
Development of radar						
signal and image	4/1/21	3/31/22	20			
conditioning algorithms	7/1/21	5/51/22	20			
through laboratory tests						
Task 7.1 (Phase 1.A).						
Documentation	4/1/21	3/31/22	50			
Task 2.3 (Phase 1 B):						
Select and configure						
securitie signal	4/1/22	9/30/22	0			
processing system						
Tagle 2.4 (Dhaga 1.D):						
A geomble ASA system						
Assemble ASA system	4/1/22	3/31/23	0			
laboratory						
Table 4 (Dhase 1 D):						
Laboratory validation						
Laboratory validation	4/1/22	3/31/23	0			
and correlation of AAS						
and radar sensors						
Task 5 (Phase I.B):						
Laboratory integration of	4/1/22	3/31/23	0			
UAV, AAS, and radar						
sensors						
Task 6.1 (Phase 1.B):	7/1/22	2/21/22	<u>_</u>			
Field modification of	7/1/22	3/31/23	0			
UAV-AAS-radar system,						



	1		
data collection, and data			
analysis			
Task 7.2 (Phase 1.B):			
Documentation,	4/1/22	3/31/23	0
dissemination, and	-1/1/22	5751725	Ū
reporting			
Task 2.5 (Phase 2):			
Integrate ASA system	4/1/23	9/30/23	0
into UAV			
Task 2.6 (Phase 2):			
Laboratory and field	1/1/23	0/30/23	0
testing of UAV with	4/1/23	9/30/23	0
integrated ASA			
Task 2.7 (Phase 2): Data			
analysis, reporting and	4/1/23	9/30/23	0
dissemination			
Task 3.3 (Phase 2):			
Modification of onboard	1/1/22	0/20/22	0
SAR imaging sensor	4/1/23	9/30/23	0
through field tests			
Task 6.2 (Phase 2): Field			
modification of UAV-			
AAS-radar system, data	4/1/23	9/30/23	0
collection, and data			
analysis			
Task 7.3 (Phase 2):			
Documentation,	4/1/22	0/20/22	0
dissemination, and	4/1/23	9/30/23	U
reporting			
Phase 1.A Overall	4/1/21	3/31/22	43.3%
Phase 1.B Overall	4/1/22	3/31/23	0
Phase 2 Overall	4/1/23	9/30/23	0

Table 2: Budget Progress University of Vermont						
Project Budget	Sp	end – Pr 6/3	oject to Date 0/21	% Project to Date 6/30/21		
Phase 1.A \$144,000	\$	\$	37,341.95	25.93%		
Phase 1.B Full Budget	0			0		
Phase 2 Full Budget	0			0		

Professional Development/Training Opportunities: NA

Technology Transfer:



Continued to communicate with Technical Champion industry partner Robert Blunt of VHB about possible field testing later this year.

Table 3: Presentations at Conferences, Workshops, Seminars, and Other Events							
Title	Event	Туре	Location	Date (s)			
Advanced Sensing Technologies for Practical UAV-Based Condition Assessment of Underside Bridge Decks	VT STIC Stakeholders Meeting and the 2021 AOT Research and Innovation Symposium	Poster and online presentation	Online	9/8- 9/2021			

Table 4: Publications and Submitted Papers and Reports						
Туре	Title	Citation	Date	Status		
NA						

Participants and Collaborators:

Table 5: Active Principal Investigators, faculty, administrators, and Management TeamMembers								
Individual Name	Individual Name Email Address Department Role in Research							
Dryver Huston	dryver.huston@uvm.edu	UVM Mech	PI					
Tian Xia	txia@uvm.edu	UVM Elec Eng	Co-PI					
Eric Landis	landis@maine.edu	UM Civil Eng	Co-PI					
Tzuyang Yu	tzuyang_yu@uml.edu	UML Civil Eng	Co-PI					

Table 6: Student Participants during the reporting period					
Student Name	Email Address	Class Major		Role in research	
Damien Garland		MS	Mech Eng	Research on UAV sensing, self-funded	
Yi Liu		MS	Mech Eng	Research on UAV sensing	



Joshua Allen	Junior	Mech Eng	Research on UAV sensing
Zahra Ameli	PhD	Civil Eng	Research on UAV sensing

Table 7: Students who Graduated During the Reporting Period						
Student Name	Student NameDegreeGraduationEmployment of continued degree					
NA						

Table 8: Research Project Collaborators during the reporting period								
		Contribution to the Project						
Organization	Location	Financial	In-Kind		Collaborative	Personnel		
_		Support Support Facilities Research E						
NA								

Table 9: Other Collaborators						
Collaborator Name and TitleContact InformationOrganization and DepartmentCo						
NA						

Who is/are the Technical Champion(s) for this project? List all. Name: Robert Blunt Title: Senior Project Manager Organization: VHB Location: South Portland, ME Email Address: rblunt@vhb.com

Changes:

Due to delays in finalizing the contracts and budgets, the project did not on the proposed date of October 1, 2020, and instead started on April 1, 2021. The task schedule listed in this report has been adjusted accordingly. No other significant changes to the project plan and scope to date.

Planned Activities:

The planned activities for the next quarter generally follow those laid out in the original proposal. These include:

1. Acoustic sensing – Continue with laboratory testing on more realistic delaminated concrete samples. Develop customized signal processing methods.



2. Microwave sensing – Configure the microwave sensor to fit on UAV and evaluate background noise. Develop customized signal processing methods.

- 3. UAV system Continue with custom UAV system development.
- 4. Field testing Attempt to conduct field tests in autumn before winter.